

ALI1 (Vdc)					
Fmax (N)	Speed (mm/s)	Version	Motor size	Motor speed (rpm)	Max Current for Fmax(A) 24Vdc**
190 *	90	M13	40	6000	2
270 *	60	M11	40	6000	2
400 *	45	M09	40	6000	2,5
580	30	M06	40	6000	2,5
1200	15	M03	40	6000	3

When speed is more than 30 mm/s and/or strokes longer than 200 mm, check STROKE SETUP section.

BEFORE OPERATING ACTUATOR MAKE SURE YOU READ AND UNDERSTOOD BASIC OPERATIONAL INSTRUCTIONS SHOWN ON USERMANUALS, AVAILABLE FROM WEBSITE.

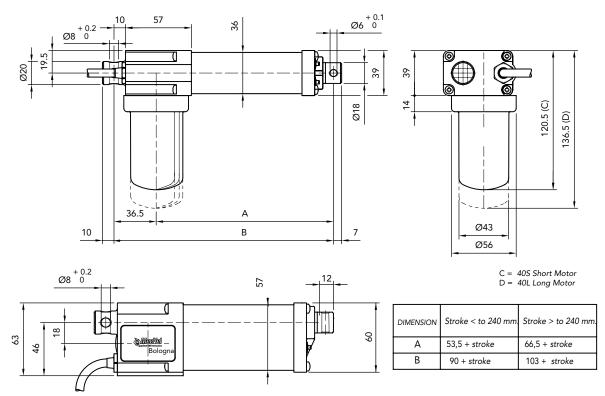
THIS DOCUMENT DISPLAYS MOST TYPICAL STANDARD FEATURES AND SETUPS: CONTACT OUR OFFICES FOR MORE.

ACTUATOR SHALL NOT COME TO MECHANICAL STROKE-END, TO AVOID FAILURES.

CONSIDER MECVEL'S LIMITSWITCHES (MODEL ALI1-F) OR PUT THEM ON MACHINE/FRAME.

^{**} For 12 Vdc power supply currents are doubled and loads are 20% lower.





ELECTRICAL WIRINGS

Options available:

C01/C08 motor

N° 2 microswitches, diode-wired C02/C09

C03/C10 motor + N° 2 micro motor + N° 3 micro C04/C11

C05/C12 motor + encoder

C06/C13 N° 2 micro diode wired + encoder C07/C14 motor + N° 2 micro + encoder

C00 special wiring (not standard options)

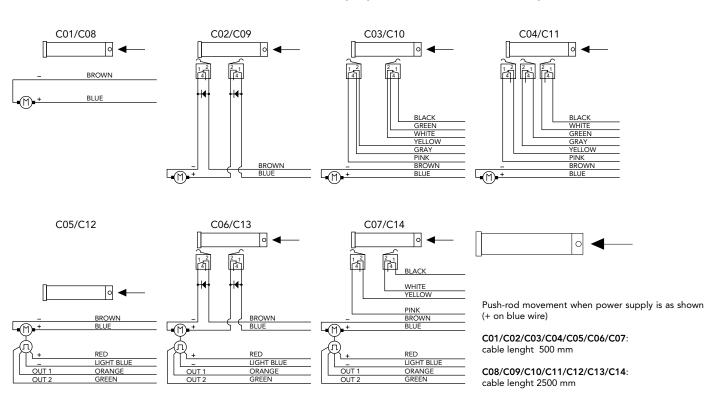
WARNING:

Micros are actuated by a cam lying on push-rod itself. Micro signal, for speeds higher than 30 mm/s, needs to be handled in its very impulse (I.E.when actuated) and not in its state. Alternatively, MecVel can add a bush to keep the microswitch lever pressed for a longer time avoiding switch signal mistakes, but cause loss of 10 mm of stroke.

Connections C02 and C06 make a circuit which stops motor supply, so that the push rod won't overstep the area of the two micros.

This system can work only if inertia generated by the actuator and load connected to it does not allow to over-step the micro when stroke is over.

So, this works just with low speeds (M01 - M03), with a load opposing the ongoing direction of the push rod. If not, relay or PLC solutions, using C03 and C07 connections, are needed... Wiring diagrams of connections above are following:





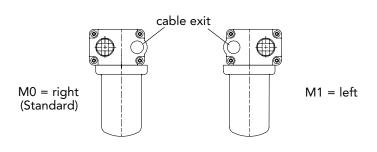
MOTOR POSITION

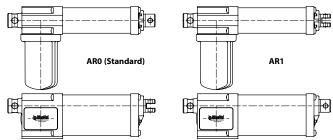
Motor can be installed on both sides of the actuator, thus achieving two versions, as show below.

The actuator is seen from backwards.

ANTIROTATION DEVICE

Model ALI1-F can host an antirotation device, allowing push rod not to spin when travelling. Front ends A1 and A2 allow for two antirotation settings, AR0 and AR1. When using A3, A4, A5 and A7 front ends antirotation facility must always be mounted.

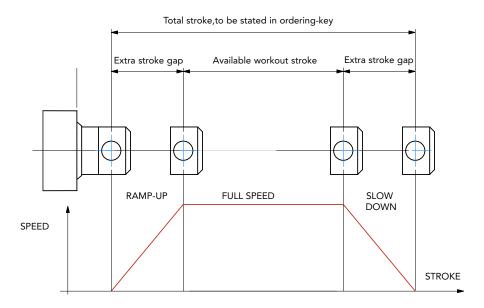




STROKE SETUP

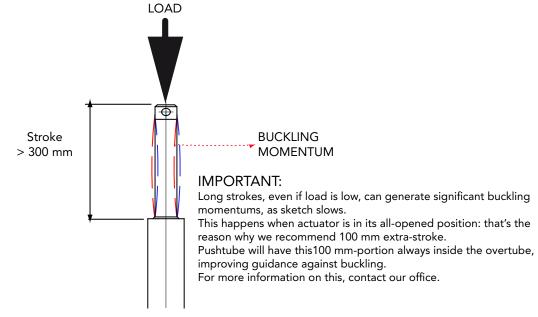
Useful tips for handling stroke and avoid run-on-block collision

- When stroke is more than 350 mm, add 50 mm extra-stroke as guidance, and put corresponding value in ordering-key WARNING SPEED-TIMING ALONG STROKELENGHT: ramps are extremely important when speed is >30 mm/s!! Inverter or PWM drive recommended!
- The more speed raises the more extra stroke has to raise too.



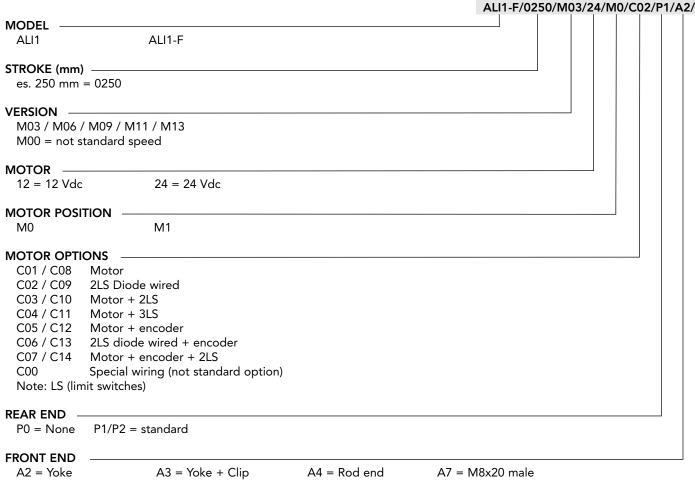
BUCKLING

When stroke is longer than 300mm, BUCKLING can be a risk: please check mounting with our offices and/or see usermanuals.

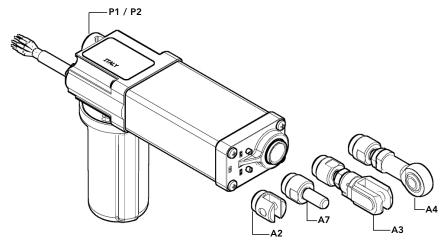




ORDERING KEY



NOTE: COMPLETE THE ORDERING KEY ADDING THE OPTIONS YOU CAN FIND IN THE "ACCESSORIES AND OPTIONS" SECTION



Note: "B" dimension changes according to model

ALI1-F = See pictures

